

A Sketch Is Worth a Thousand Words: Image Retrieval with Text and Sketch

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Abstract. We address the problem of retrieving in-the-wild images with *both a sketch and a text query*. We present TASK-former (Text And SKetch transformer), an end-to-end trainable model for image retrieval using a text description and a sketch as input. We argue that both input modalities complement each other in a manner that cannot be achieved easily by either one alone. TASK-former follows the late-fusion dual-encoder approach, similar to CLIP [35], which allows efficient and scalable retrieval since the retrieval set can be indexed independently of the queries. We empirically demonstrate that using an input sketch (even a poorly drawn one) in addition to text considerably increases retrieval recall compared to traditional text-based image retrieval. To evaluate our approach, we collect 5,000 hand-drawn sketches for images in the test set of the COCO dataset. The collected sketches are available at <https://janesjanes.github.io/tsbir/>.

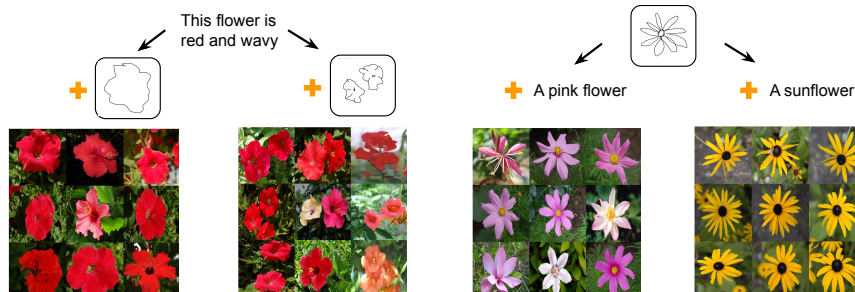


Fig. 1: We present TASK-former, a Text And SKetch transformer based method for image retrieval. We demonstrate that the presence of a sketch input, even a poorly drawn one, helps narrow down the set of retrieved images to ones that match the joint description provided by the sketch and the text query. Retrieval results are from our model trained on Flower102 dataset [29]

1 Introduction

Cross-modal retrieval [44] is a retrieval problem where the query and the set of retrieved objects take different forms. A representative problem of this class is Text-Based Image Retrieval (TBIR), where the goal is to retrieve relevant images from an input text query. TBIR has been studied extensively, with recent interest focused on transformer-based models [36]. A core component of a cross-modal retrieval model is its scoring function that assesses the similarity between a text description and an image. Given a text description, retrieving relevant images then amounts to finding the top k images that achieve the highest scores.

While a text description is suitable for describing qualitative attributes of an object (e.g., object color, object shape) in TBIR, it can be cumbersome when there is a need to describe multiple objects or a complex shape. Consider the query “This flower is red and wavy” in Figure 1 as an example. This query alone can match red flowers of a wide range of shapes. Further, with multiple objects, it becomes necessary to describe their relative positions, making the task too cumbersome to be practical. These limitations naturally led to a related thread of research on Sketch-Based Image Retrieval (SBIR), where the goal is to retrieve images from an input sketch [38, 31, 47, 13, 32, 50, 37]. Compared to text, specifying object positions with a hand-drawn sketch is relatively easy.

Recent works on SBIR tend to focus on a specific set of retrievable images. For instance, [38] considers object based retrieval: each image has only one object centered in the image. Compared to [38], [47] allows a more free-form sketch input, but from a single category e.g., shoes. While suitable for an e-commerce product search, searching from an arbitrarily drawn sketch, also known as *in-the-wild SBIR*, was not studied in [47]. In-the-wild image retrieval is the problem we tackle in this work.

In-the wild SBIR presents two challenges. Firstly, there is semantic ambiguity in a sketch drawn by a non-artist user. To a non-artist, it takes effort to draw a sketch which sufficiently accurately represents the desired image to retrieve. While adding details to the sketch would naturally narrow down the candidate image set, to a non-artist user, the extra effort required to do so may outweigh the intended convenience of SBIR. Ideally the retrieval system should be able to extract relevant information from a poorly drawn sketch. Secondly, the few publicly available SBIR datasets contain only either images of single objects [38, 47], or images describing single concepts [18]. These images are different from target images in in-the-wild image search, which may contain multiple objects with each belonging to a distinct category.

In this work, we address these two challenges in in-the-wild image retrieval by proposing to *use both a sketch and a text query as input*. The (optional) input sketch is treated as a supplement to the text query to provide more information that may be difficult to express with text (e.g., positions of multiple objects, object shapes). In particular, we do not require the input sketch to be drawn well. As will be seen in our results, when coupled with a text query, an extra input sketch (even a poorly drawn one) can help considerably narrow down the set of candidate images, leading to an increase in retrieval recall. We show

that both input modalities can complement each other in a manner that cannot be easily achieved by either one alone. To illustrate this point concretely, two example queries can be found in Figure 1 where dropping one input modality would make it difficult to retrieve the same set of images. This idea directly addresses the first challenge of in-the-wild SBIR – sketch ambiguity.

Combining two input modalities is made possible with our proposed similarity scoring model, *TASK-former*, which follows the late-fusion dual-encoder approach, and allows efficient retrieval (see Figure 2 for the model and our training pipeline). Our proposed training objective comprises 1) an embedding loss (to learn a shared embedding space for text, sketch, and image); 2) a multi-label classification loss (to allow the model to recognize objects) ; and 3) a caption generation loss (to encourage a strong correspondence between the learned joint embedding and text description). Crucially, training our model only requires synthetically generated sketches, not human-drawn ones. These sketches are generated from the target images, and are further transformed by appropriate augmentation procedures (e.g., random affine transformation, dropout) to provide robustness to ambiguity in the input sketch. The ability of our model to make use of synthetically generated sketches during training addresses the second challenge of in-the-wild SBIR – lack of training data. We show that our model is robust to sketches with missing strokes (Figure 5), and is able to generalize and operate on human-drawn input sketches (Figure 4).

Our contributions are as follows.

1. We present TASK-former (Text And SKetch transformer), a scalable, end-to-end trainable model for image retrieval using a text description and a sketch as input.
2. We collect 5000 hand-drawn sketches for images in the test set of COCO [27], a commonly used dataset to benchmark image retrieval methods. The collected sketches are available at <https://janesjanes.github.io/tsbir/>.
3. We empirically demonstrate (in Section 4) that using an input sketch (even with a poorly drawn one) in addition to text helps increase retrieval recall, compared to the traditional TBIR where only a text description is used as input.

2 Related Work

Sketch Based Image retrieval (SBIR) There are several works that tackle SBIR [38, 31, 47, 13, 32]. The works of [31, 10, 42, 28, 13] consider zero-shot SBIR where retrieving from unseen categories is the focus. Zhang et al. [48] tackles SBIR using only weakly labeled data. Fine-grained SBIR of a restricted set of images (e.g., from a single category) is studied in [32, 39, 33]. An interactive variant of SBIR was considered in [8] where images are retrieved on-the-fly as an input sketch is being drawn. They propose a form of sketch completion system for SBIR based on user’s choice of image cluster to refine the retrieval results. Bhunia et al. [3] present a reinforcement learning based pipeline for SBIR and allows a retrieval even before the sketch is completed. Being able to retrieve relevant images even

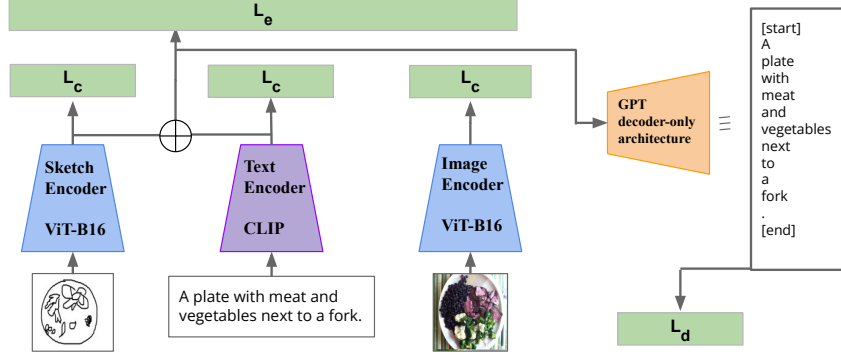


Fig. 2: Overview of our model and the training pipeline. ViT is the vision transformer [12], and \oplus represents an element-wise addition. We extend CLIP [35] to incorporate additional sketch input from user. We add two auxiliary tasks: multi-label classification (L_c) and caption generation (L_d). Our objective losses are explained in Section 3.2. We encourage the network to learn a discriminative representation to simultaneously distinguish at the instance level and at the category level, both of which are crucial for a successful retrieval.

with incomplete sketch information is an important aspect of SBIR. In this work, we achieved this by supplementing the (incomplete) sketch with an input text description.

Text-based image retrieval (TBIR) The problem of retrieving images based on a text description is closely related to the ability to learn a good representation between these two different domains. Previous successes in TBIR relied on the cross attention mechanism (a specific form of early fusion) to learn the similarity between text and images [49, 24, 26]. It is generally believed that, compared to a late fusion model, an early fusion model can offer more capacity for modeling a complex scoring function owing to its non-factorized form [46, 1]. Interestingly however the recently proposed CLIP [35], a late fusion model, is able to achieve comparable TBIR results on COCO to existing early fusion models. This feat is impressive and is presumably due to the use of a large proprietary dataset of text-image pairs crawled from the Internet. The representation learned by CLIP is incredibly rich, and correlates well with human perception on image-text similarity as observed in [17].

Similar to CLIP, ALIGN [20] also proposes a similar contrastive training scheme on a large-scale data. Fine-tuning from a pre-trained network in ALIGN is able to achieve state-of-the-art (SOTA) accuracy of 59.9% in retrieving a single correct image based on text description in the COCO image retrieval benchmark (karpthy split).⁴ In our work, we opt to use the pre-trained CLIP network to initialize our network for training.

⁴ More recently, Microsoft team also presented T-Bletchley [41] with a similar pipeline.

Image retrieval with multi-modal queries Using text and image as queries for image retrieval has been explored extensively in the literature, for example as a textual instruction for a desired modification of the query image [40, 43, 16, 6, 11]. Jia et al [20] demonstrate that it is possible to directly combine representations of the two input modalities (text and image in this case) with a simple element-wise addition, for the purpose of image retrieval with maximum inner product search. In our work, we take this insight and combine the representation of sketch and text inputs in the same way. Using a sketch as input which is further supplemented by additional information (such as a classification label) has also been studied in Sketch2Tag [45] and Sketch2Photo [5]. Instead of sketch, [4] explores using fine grain association between mouse trace and text description for image retrieval. Surprisingly, combining sketch and full text description as queries for image retrieval has been relatively under explore despite its potential usefulness. [9, 15, 21] explore the benefit of training with both sketch and text inputs for the purpose of improving image retrieval performance for each modality separately. Only [21] demonstrate examples of retrieving with both sketch and text inputs by linearly combining their score during test time. Note that unlike ours, the proposed loss function of [21] does not explicitly consider interactions between sketch and text inputs, since the goal is to simply improve retrieving with each modality separately. Further to find the similarity between a sketch and a given image, the proposed method of [21] requires that the image be first converted to a sketch via edge detection. This conversion would incur a loss of information such as the color. The proposed method also requires a conversion of image into sketch via edge detection, and would lose color information which is not ideal. While [21] is one of the most related works to our work, we are unfortunately not able to obtain the data used, or the trained model for a quantitative comparison.

3 Proposal: TASK-former

TASK-former can be considered an extension of the training pipeline proposed in CLIP [35]. We start with the same network architectures and contrastive learning as in CLIP, but modify them and add additional loss terms to allow the use of both a sketch and an input text query. Specifically, we include two additional auxiliary tasks: multi-label classification and caption generation. Our motivation is to improve the learned embedding space so as to achieve the following goals.

1. Discriminate between the positive and negative pairs;
2. Distinguish objects of different categories; and
3. Contain sufficient information to reconstruct the original text caption from embeddings of an image and its sketch.

We achieve these goals via CLIP’s symmetric cross entropy, multi-label classification objective, and caption generation objective, respectively. While these three objectives appear to seek conflicting goals (e.g., the classification loss might encourage discarding class-invariant information, whereas the image captioning

loss would suffer less if all describable details are kept), we observe that combining them with appropriate weights can lead to gains in performance for image retrieval as shown in Table 2.

We start by describing our model and training pipeline in Section 3.1, and describe the three aforementioned loss terms in Section 3.2.

3.1 Model and Training Pipeline

Our pipeline is summarized in Figure 2. Each input query consists of 1) a hand-drawn sketch, and 2) a text description of desired target images. We use the same image and text encoder architecture as described in CLIP [35] in order to leverage networks that have been pre-trained with large-scale training data. This choice is in accord with the common practice of using, for instance, an ImageNet pre-trained network for various vision tasks. We use CLIP’s publicly available pre-trained model ViT-B/16, in which the image encoder is based on the Vision Transformer [12] which we found to be the best performer for our task. For the details of the network architecture of each encoder that we use, please refer to CLIP [35] and ViT [12].

There are three encoders in our pipeline for: 1) input sketch, 2) input text description, and 3) a candidate retrieved image. The output embeddings from the sketch and the text encoders are combined together and used for contrastive learning with the image embedding as the target. We explore several options for combining features in Section 4.1. Since images and sketches are in the same domain (visual), we use the same architecture for them (ViT-B/16 pre-trained on CLIP). We also found that the performance is much better when sharing weight parameters across the sketch and the image encoders. Yu et al. [47] also observed similar results where the Siamese network performs significantly better than heterogeneous networks for the SBIR task. It was speculated that weight sharing is advantageous because of relatively small training datasets. This explanation may also hold in our case as well given the complexity of our task. For classification, we feed each embedding to two additional fully connected layers with ReLU activation.

Additionally, we also train a captioning generator from the embeddings of sketches and images using a transformer based text decoder. This decoder is an autoregressive language model similar to GPT decoder-only architecture [36]. We use absolute positional embedding, with six stacks of decoder blocks, each with eight attention heads. More details can be found in the supplementary materials.

3.2 Objective Function

Our objective function consists of three main components: symmetric cross entropy, asymmetric loss for multi-label classification, and auxiliary caption generation.

Embedding Loss (L_e) To learn a shared embedding space for text, image and sketch, we follow the contrastive learning objective from CLIP [35], which use a

form of *InfoNCE Loss* as originally proposed in [30] to learn to match the right image-text pairs as observed in the batch. This proxy task is accomplished via a symmetric cross entropy loss over all possible pairs in each batch, effectively maximizing cosine similarity of each matching pair and minimizing it for non-matching ones. We add the sketch as an additional query, and replace the text embedding in CLIP with our combined embedding constructed by summing the text and sketch embeddings.

Classification Loss (L_c) For classification, we consider this as a multi-label classification problem as each image can belong to multiple categories. We follow a common practice in multi-label classification, which frames the problem as a series of many binary classification problems. We use object annotation available in the datasets as ground truth. Specifically, we use Asymmetric Loss For Multi-Label Classification (ASL Loss), proposed in [2]. The loss is designed to help alleviate the effect of the imbalanced label distribution in multi-label classification.

Auxiliary caption generation (Decoder Loss, L_d) For caption generation, the decoder attempts to predict the most likely token given the accumulated embedding and the previous tokens. The decoded output tokens are then compared with the ground truth sentences via the cross entropy loss $\sum_t^T \log(p_t|p_1, \dots, p_{t-1})$, where T is the maximum sequence length.

Our final objective is given by a weighted combination of all the loss terms. We refer to supplementary materials for our hyperparameter choices.

3.3 Sketch Generation and Data Augmentation

During training, we synthetically generate sketches using the method proposed in [25]. In general the method produces drawings similar to human sketches. The synthesized sketches are however in exact alignment with their source images, which would not be the case in sketches drawn by humans. To achieve invariance to small misalignment, we further apply a random affine transformation on the synthetic sketch as an augmentation. We also apply a similar transformation to the image (with different random seeds). Introducing this misalignment is crucial for the network to generalize to hand-drawn input sketches at test time.

To help deal with partial sketches at test time, we also randomly occlude parts of each sketch. We randomly replace black strokes with white pixel. The completion level of each synthesized sketch in the training set is between 60% to 100%

Evaluation with sketch-text-image tuples Since our approach retrieves images with sketches and text, evaluating our approach naturally requires an annotated dataset where each record contains a hand-drawn sketch, a human-annotated text description, and a source image. SketchyCOCO [14] fits this description and is a candidate dataset. However, the dataset was constructed by having the sketches drawn first based on categories. The sketch for each category was then

pasted into their supposed areas based on incomplete annotation (not all objects were annotated). As a result, the sketch in each record may poorly represent the image because 1) each category contains the same sketch, 2) the choice of which object to draw is based on categories, rather than human judgement of what is salient in each particular image. More related is the dataset mentioned in [21] which provides 1,112 matching sketch/image/text of shoes. However, the dataset is not yet available at the time of writing. Also worth mentioning is [34], which also proposes a dataset containing synchronized annotation between text description and the associated location (in a form of mouse trace) in the image. However, we argue that a line drawing sketch represents more than just the location of the objects; even a badly drawn sketch can provide information such as shape, details, or even relative scale. Owing to lack of an appropriate evaluation dataset, we construct a new benchmark by collecting hand-drawn sketches for images in the COCO image retrieval benchmark. These images are in the COCO 5k split from [22], which is widely used to evaluate text based image retrieval methods. As part of our contributions, the collected data will be made publicly available. We describe the sketch collection process in the next section.

3.4 Data Collection: Sketching from Memory

We collect sketches for COCO 5k via Amazon Mechanical Turk crowd sourcing platform (AMT). We follow the split from [22], which has been widely used as benchmark for text based image retrieval. The test set contains 5000 images which are disjoint from the training split.

To solicit a sketch, we first show the participant (Turker) the target image for 15 seconds, before replacing it with a noise image. This is to mimic the typical scenario at deployment time where there is no concrete reference image, but instead only a mental image of a retrieval target. The participant is then asked to draw a sketch from memory. In the instructions, we ask the participants to draw as if they are explaining the image to a friend but using a sketch. We do not put any restrictions on how the sketch has to be drawn, other than no shading. The participants are free to draw any parts of the image they think are important and distinctive enough to be included in the sketch. The sketches are collected in SVG (a vector format), and contain information of all individual strokes. In experiments, we use this information to randomly drop individual strokes to test the robustness of our approach to incomplete input sketches (see Figure 5). As a sanity check, we also ask the participants to put one or two words describing the image in an open-ended fashion.

From the results, we manually filter out sketches that are not at all representative of the target image (e.g., empty sketch, random lines, wrong object). Our only criteria is that each sketch has to be recognizable as describing the target image (even if only remotely recognizable). Our goal is not to collect complete or perfect sketches, but to collect in-the-wild sketches, which may be poorly drawn, that can be used along side the text description to explain image.

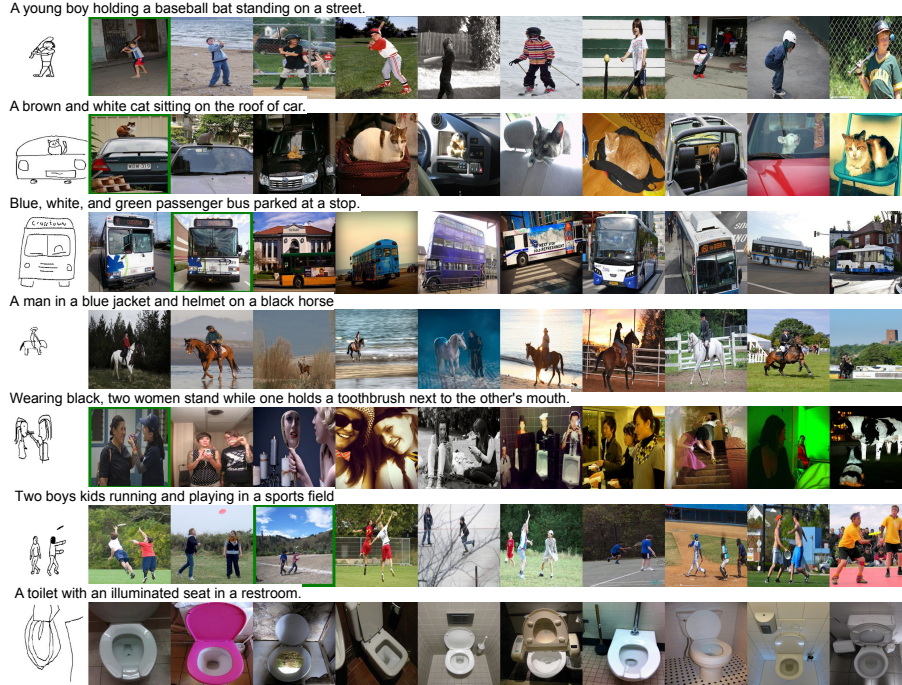


Fig. 3: Example retrieved images from TASK-former, randomly selected from our benchmark. Each query consists of a text description (shown at the top of each block, and an input sketch (at the top left of each block). In each case, the image that forms a matching pair to the sketch is highlighted with a green border. See Section 3.4 for details on how we collect human drawn sketches for images in the evaluation set.

4 Results and Discussion

For quantitative evaluation, we calculate Recall@K, which is the fraction of times that the target image is included in the top-K retrieved images. We evaluate on COCO [27]; a commonly used datasets for language based image retrieval. We use the same data split as proposed in [22]. Specifically, COCO’s evaluation set contains 5,000 images. Each image is annotated with multiple captions, and we additionally add a sketch to each image. For COCO, we collect hand drawn sketch as described in 3.4.

Implementation details We use Adam [23] as the optimization method to train the model. Training hyperparameters are set in accordance with Open Clip [19] with the initial learning rate set to 10^{-5} . To provide robustness to incomplete input, for each (text query, sketch, image) training tuple, we set a 20% probability to drop either the sketch (replaced with a white image) or the text query

Table 1: Recall@{1, 5, 10} of state-of-the-art methods on COCO dataset. We use our collected hand-drawn sketches for evaluation. Among ALIGN, and CLIP, only CLIP has released pre-trained model. Our TASK-former is initialized for training with this CLIP model.

Type	Method	Input	R@1	R@5	R@10
Early fusion	Uniter [7]	Text	0.529	0.799	0.880
Early fusion	OSCAR [26]	Text	0.575	0.828	0.898
Dual encoders	ALIGN [20] (fine-tuned)	Text	0.599	0.833	0.898
Dual encoders	CLIP [35] (fine-tuned)	Text	0.518	0.811	0.891
Dual encoders	TASK-former (ours)	(Text, Sketch)	0.609	0.847	0.917

(replaced with an empty text). We demonstrate the robustness of our model to incomplete input in Section 4.2. Code to reproduce our results will be made publicly available.

For evaluation, our model TASK-former is initialized with the publicly released CLIP model (ViT-16) [35], a text-based image retrieval model. Table 1 compares Recall@{1, 5, 10} of our method and that of current state-of-the-art approaches on text based image retrieval: Uniter, OSCAR, and ALIGN as reported in [7, 20, 26], respectively. To provide a fairer comparison, we further finetune the publicly released CLIP model (ViT-16) on COCO.⁵ We observe that our method is able to achieve a considerably higher recall than other methods, and CLIP in particular, owing in part to the use of a sketch as a supplemental input to text. Our method can retrieve the correct image with recall@1 of 60.9%, compared to using text alone, which achieves 51.8% on the same CLIP architecture (ViT-16).

At the time of writing, models for ALIGN and T-Bletchley have not been released. Both methods have been shown to perform better than CLIP on text based image retrieval, and without any early fusion of text and image. We note that both ALIGN and T-Bletchley can be used as part of our framework by simply replacing the pre-trained encoders for text and image.

4.1 Ablation Study

In this section, we seek to understand the effect of each of our proposed loss functions (L_e, L_c, L_d), as described in Section 3. Baselines used as part of this ablation study are:

- **CLIP zero shot.** Recall@K that has been reported in [35] for zero-shot image retrieval. We note that their best model for the reported results (ViT-L/14@336px) is not available publicly.

⁵ Note that this baseline makes use of our best-effort implementation and training. We do not have access to the official training code and there is no reported result on using a fine-tuned CLIP on an image retrieval dataset.

Table 2: Results from our ablation study as described in Section 4.1. We construct variants of our proposed method by selectively including only some training losses. These are denoted by L_e , $L_e + L_c$, and $L_e + L_c + L_d$ (see Section 3.2). Sketch and text inputs are combined by adding their embeddings. For “Feature max” and “Feature concat”, the embeddings are combined by coordinate-wise maximum, and concatenation, respectively, and the full objective is used.

Method	R@1	R@5	R@10
CLIP (zero shot)	0.378	0.624	0.722
Ours: L_e	0.493	0.748	0.836
Ours: $L_e + L_c$	0.509	0.764	0.850
Ours: $L_e + L_c + L_d$	0.527	0.778	0.862
Ours: Feature max	0.443	0.704	0.804
Ours: Feature concat	0.357	0.650	0.768
Ours (final)	0.609	0.847	0.917

- **Ours: L_e** (ablated TASK-former). We start adding a sketch as an additional query, as shown in Figure 2. The only objective in this baseline is to correctly classify the correct matching pair between the query (sketch+text) and the image via *symmetric cross entropy loss*.
- **Ours: $L_e + L_c$** (ablated TASK-former). In this baseline, we add the multi-label classification loss term in the objective.
- **Ours: $L_e + L_c + L_d$** (ablated TASK-former). In this baseline, we add both classification loss and decoder loss

For the above three baselines, text and sketch embeddings are combined by adding them, as described in Figure 2. We further compare two additional ways to combine sketch and text embeddings: coordinate-wise maximum, and concatenation:

- **Ours: Feature max** (ablated TASK-former). Embeddings from sketch and text are combined using element-wise max.
- **Ours: Feature concatenate** (ablated TASK-former). Embeddings from sketch and text are concatenated, and projected into the same dimension as embedding from image.

We use the full objective (i.e., $L_e + L_c + L_d$) for the above two variants.

- **Ours (final)** This is our complete model trained with the full objective ($L_e + L_c + L_d$). We augment training sketches and images with random affine transformation, randomly remove parts of each sketch (as describe in Sec. 3) and train for 50 epochs.

Except for the final model, we train each baseline for 10 epoches. For ablation study, we simplify the training by only performing simple augmentation (random cropping and flipping).



Fig. 4: Some retrieved images by our model when using only a sketch query, only a text query, and with both queries at the same time. Our model is robust to missing input: when only one input modality is present, it can still retrieve relevant image, albeit suboptimally. We observe that the presence of an input sketch clearly helps rank the most relevant image higher.

Table 2 reports recalls of each baselines. Both L_c and L_d further improve the retrieval performance compare to our baseline with only embedding loss (L_e). Surprisingly, our experiment also show that a simple element wise addition leads to the best performance compare to element wise max, and concatenation. We hypothesize that direct combination of the sketch and text embedding implicitly helps with feature alignment, compare to concatenate them.

4.2 Robustness to Missing Input

One key benefit of our pipeline is the ability to retrieve image even when missing one of the input modalities (sketch or text). We accomplish this by adding a query drop-out augmentation which replaces either the sketch or text with an empty sketch or an empty string. This ensures the network can operate even when no sketch or text description is given. Figure 4 shows the results breaking








Ground truth image	100%	80%	60%	40%	20%	0%
						
Sketch completeness	100%	80%	60%	40%	20%	0%
R@1	.615	.609	.602	.582	.515	.458
R@5	.883	.876	.870	.843	.833	.776
R@10	.947	.926	.940	.923	.916	.870

Fig. 5: Recall@{1, 5, 10} of TASK-former, averaged over 300 randomly sampled (text query, sketch, image) tuples in the COCO dataset. For each test instance, we vary the completeness of the sketch, where completeness level $x\%$ is defined as the original sketch with only $x\%$ of all strokes randomly chosen. Candidate retrievable images are the full COCO test set of 5k. The completeness 0% corresponds to using only text as input. We observe that even with a small fraction of strokes retained (e.g., 20%), there is gain in recall compared to using only text as input (i.e., 0% sketch completeness)

down into querying with sketch only, querying with text only, and querying with both modalities. We emphasize that sketch based image retrieval is particularly challenging for unconstrained, in-the-wild images with multiple objects and no fixed categories. In spite of that, our network can retrieve reasonably relevant results for sketch query alone, all without requiring any hand drawn sketch during training.

Nevertheless, we find that using the sketch or text as a sole input is often sub-optimal for image retrieval in this setup. A combination of sketch and text can provide a more complete picture of the target image, leading to an improve performance. For instance, in the first example of Figure 4, it can be difficult to draw a *brown* desk with sketch alone, but this can be included easily with text description.

4.3 Sketch Complexity and Retrieval Performance

In this section, we investigate the effect of varying the level of sketch details on the retrieval performance. We sample 300 sketches from our collected COCO hand-drawn sketches, and randomly subsample strokes to keep only 20% to 100%. Table 5 shows the recall performance on each level of sketch complexity. We observe a large gain near the lower end of the completeness level, with a diminishing gain as the completeness level increases. In particular, this suggests that even a poorly drawn sketch helps in retrieving more relevant images. We observe that reducing the sketch completeness level from 100% to 60% only slightly decreases recall.

Table 3: Retrieval performance of our model as measured by $\text{recall@}\{1, 5, 10\}$ when both a complete sketches, and text queries are inputted to the model. Words in each text query are sub-sampled to investigate the effect of incomplete input text on retrieval.

Text completeness	R@1	R@5	R@10
0%	0.099	0.195	0.257
20%	0.316	0.545	0.640
40%	0.357	0.613	0.708
60%	0.446	0.710	0.813
80%	0.530	0.807	0.884
100%	0.607	0.866	0.930

4.4 On the Effect of Text Completeness

In Section 4.3, we investigate the effect of an incomplete input sketch on the retrieval recall. The goal of this section is to provide an analogous analysis on the effect of an incomplete text input. We sample 300 records of from our collected COCO dataset. Each record consists of three objects: a sketch, a text description, and an image. For each text description, we vary its degree of completeness by randomly subsampling $x\%$ (for a number of values of x) of the tokens (words), while keeping its corresponding sketch intact. Table 3 shows the resulted retrieval recall for each degree of text completeness. We observe that compared to when no text query is given as an input (0%), recall@1 increases from 0.099 to 0.316 when only 20% of tokens are included. The gain in recall diminishes as more tokens are added.

5 Limitations and Future Work

Figure 3 shows the potentials of our retrieval model. However, it also reveals some examples of when our method fails to retrieve the target image. For example, in the forth row, the network is unable to retrieve the correct image (with blue jacket and black horse). This is likely due to the confusion with the color (both black and blue color are in the text description). While the network does place images with both black and blue color closer to the query embedding, it is unable to find the target image with black horse, and blue jacket within the top 10 results. This shows the current limitation of the model in understanding complicated text description.

Beyond these examples, we generally observe that the network suffers when the sketch is not representative of the target image. For example, the difference in scale and location can contribute to incorrect retrieval results (sixth row of Figure 3). Designing a model that is more tolerant to scale mismatch will be an interesting topic for future research. On the text encoder, automatically augmenting the text query to be more concrete by leveraging text augmentation techniques also deserves further attention.

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